Supplementary Material for "Improved Variational Denoising of Flow Fields with Application to Phase-Contrast MRI Data"

Proof of Proposition 1. Let us first remark that in Fourier domain

$$\mathcal{F}{\mathbf{J}\mathbf{f}}(\boldsymbol{\omega}) = \hat{\mathbf{f}}\mathbf{j}\boldsymbol{\omega}^{\top},$$

where $\hat{\mathbf{f}}$ is the Fourier transform of \mathbf{f} . For the scaling invariance, we note that the scaling operator $\mathbf{S}_a : \mathbf{f} \mapsto \mathbf{f}(\cdot/a)$ commutes with the Jacobian (up to a multiplicative constant) as it holds that

$$\mathcal{F}{\mathbf{J}{S_a \mathbf{f}}}(\boldsymbol{\omega}) = |a|^d \hat{\mathbf{f}}(a\boldsymbol{\omega}) \mathbf{j}\boldsymbol{\omega}^\top$$
$$= (1/a) \left(|a|^d \hat{\mathbf{f}}(a\boldsymbol{\omega}) \mathbf{j}(a\boldsymbol{\omega})^\top \right)$$
$$= (1/a) \mathcal{F}{\mathbf{S}_a{\mathbf{J} \mathbf{f}}}(\boldsymbol{\omega}).$$

Since the Schatten p-norms are 1-homogeneous functions, we obtain that

$$\begin{aligned} \mathrm{TV}_p(\mathrm{S}_a \mathbf{f}) &= \frac{1}{|a|} \int_{\mathbb{R}^d} \| \{ \mathbf{J} \mathbf{f} \}(\mathbf{x}/a) \|_{\mathcal{S}_p} \, \mathrm{d} \mathbf{x} \\ &= |a|^{d-1} \int_{\mathbb{R}^d} \| \mathbf{J} \mathbf{f}(\mathbf{u}) \|_{\mathcal{S}_p} \, \mathrm{d} \mathbf{u} \\ &= |a|^{d-1} \, \mathrm{TV}_p(\mathbf{f}), \end{aligned}$$

where the second equality follows from a simple change of variables.

As for rotation by a matrix ξ , we have (\mathbf{R}_{ξ} is the rotation operator)

$$\begin{split} \mathcal{F}\{\mathbf{J}\{\mathbf{R}_{\xi}\mathbf{f}\}\}(\boldsymbol{\omega}) &= \xi \hat{\mathbf{f}}(\xi\boldsymbol{\omega})\mathbf{j}\boldsymbol{\omega}^{\top} \\ &= \xi \hat{\mathbf{f}}(\xi\boldsymbol{\omega})\mathbf{j}\boldsymbol{\omega}^{\top}\xi^{\top}\xi \\ &= \xi \hat{\mathbf{f}}(\xi\boldsymbol{\omega})\mathbf{j}(\xi\boldsymbol{\omega})^{\top}\xi \\ &= \mathcal{F}\{\mathbf{R}_{\xi}\{\mathbf{J}\mathbf{f}\}\xi\}(\boldsymbol{\omega}). \end{split}$$

Then, we write that

$$\begin{aligned} \mathrm{TV}_p(\mathrm{R}_{\xi}\mathbf{f}) &= \int_{\mathbb{R}^d} \left\| \mathbf{J}\{\mathrm{R}_{\xi}\mathbf{f}\}(\mathbf{x}) \right\|_{\mathcal{S}_p} \mathrm{d}\mathbf{x} \\ &= \int_{\mathbb{R}^d} \left\| \xi^{\top}\{\mathbf{J}\mathbf{f}\}(\xi\mathbf{x})\xi \right\|_{\mathcal{S}_p} \mathrm{d}\mathbf{x} \\ &= \int_{\mathbb{R}^d} \| \mathbf{J}\mathbf{f}(\xi\mathbf{x}) \|_{\mathcal{S}_p} \,\mathrm{d}\mathbf{x}, \end{aligned}$$

since the Schatten norms are unitarily invariant¹. Now, applying a change of variable $\mathbf{u} = \xi \mathbf{x}$, with $d\mathbf{u} = |\det \xi| d\mathbf{x} = d\mathbf{x}$, we arrive at the desired result:

$$\mathrm{TV}_p(\mathbf{R}_{\boldsymbol{\xi}}\mathbf{f}) = \mathrm{TV}_p(\mathbf{f})$$

Translation invariance is straight forward to show by using a change of variable. $\hfill \Box$

¹R. Bhatia, Matrix Analysis. Springer, 1997.