

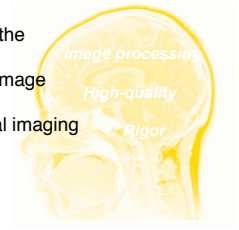
Recent advances in image processing for bio-photonics

Michael Unser

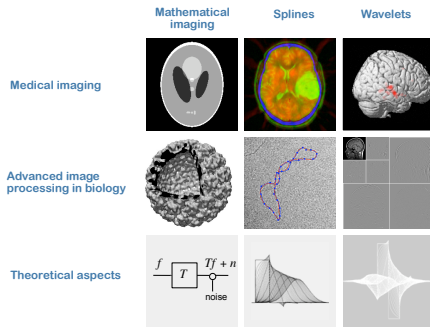
Biomedical Imaging Group
Institute of Imaging and Applied Optics
EPFL, Lausanne, Switzerland

Biomedical Imaging Group (BIG)

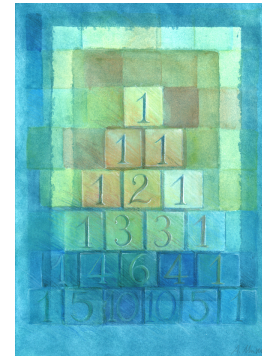
- Institute of Imaging and Applied Optics (IOA)
- BIG: 10-15 people
- Activities
 - Image processing tools for the biomedical community
 - Mathematical methods for image processing
 - Digital optics, computational imaging
- Research
- Teaching



Research strategy



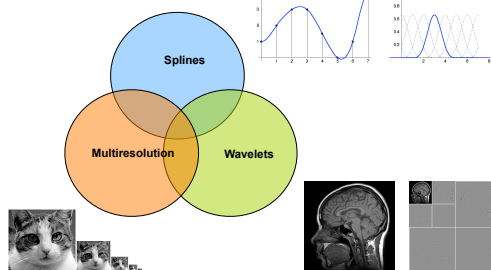
RESEARCH: Fundamental aspects



Splines and wavelets

Splines: a unifying perspective

Linking the discrete and the continuous



RESEARCH: Image processing in biology

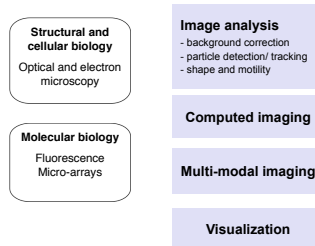


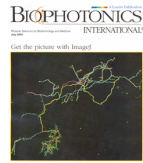
IMAGE ANALYSIS



- Particle tracking (*D. Sage*)
 - Collaboration with S. Gasser



- Neuron tracing (*E. Meijering*)
 - Collaboration with H. Hirling, J.-C. Sarria

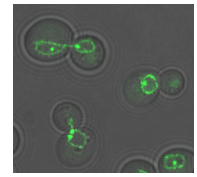


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Single particle tracking

- Study of yeast nuclear dynamic

- Goal: analysis of the movement of a tagged chromosomal locus within the nucleus
- GFP Labeling



- Time-lapse microscopy: 1 frame per 1.5 s
- Nuclear $\varnothing \approx 2 \mu\text{m}$

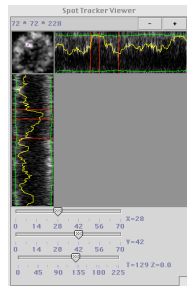


Data: Prof. S. Gasser
Dept. Molecular Biology
University of Geneva

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Single particle tracking: the solution

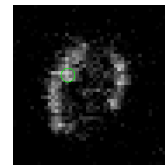
- Problem-specific constraints
 - Particle signature: bright, round spot
 - Smooth trajectory
 - Movement constrained to within the nucleus
- Algorithmic solution
 - Global optimization (DP) : past + future
 - Cost function trade-offs
 - Favors bright (or spot-like) structures
 - Imposes continuity constraints
 - Penalizes large jumps
 - Penalizes proximity to the nuclear boundary
 - Automatic or semi-automatic mode
 - Can accept user-constraints
 - Editing of solution



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Single particle tracking: results

- Features
 - Ease-of-use: 1 to 5 clicks
 - Automatic alignment
 - 5 seconds to track a spot over 300 images
 - Tuning of the cost function
- Advantages
 - Reduction of work load
 - Reproducibility
- Extensions
 - 3D tracking
 - Multiple particles

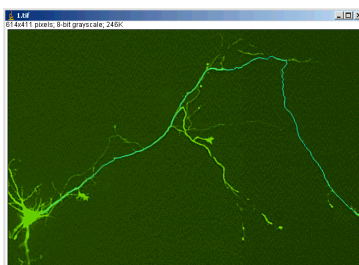


Sage et al., *IEEE Trans. Image Processing*, submitted

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Tracing neurons...

- Semi-automatic approach: "livewire"
 - Optimal path between A and B (mouse clicks)
 - Minimization of a cost function
 - Dijkstra shortest path algorithm



Collaboration with H. Hirling, EPFL

Meijering et al., *Cytometry*, 2004.

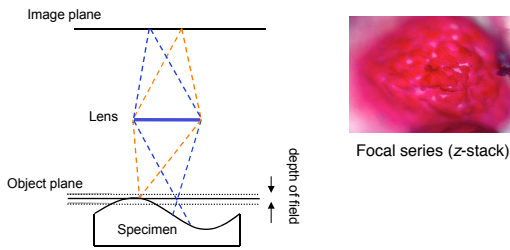
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MATHEMATICAL IMAGING

- Extended depth-of-field (*B. Forster*)
 - Collaboration with ISREC
- Super-resolution microscopy (*F. Aguet*)
 - Collaboration with N. Garin
- Super-resolution OCT (*T. Blu, R. Langoju*)
 - Collaboration with S. Bourquin, R. Salathé

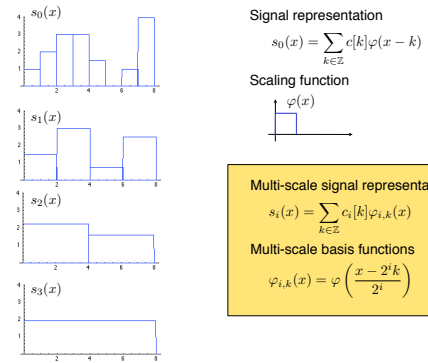
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Limited depth-of-field: the problem



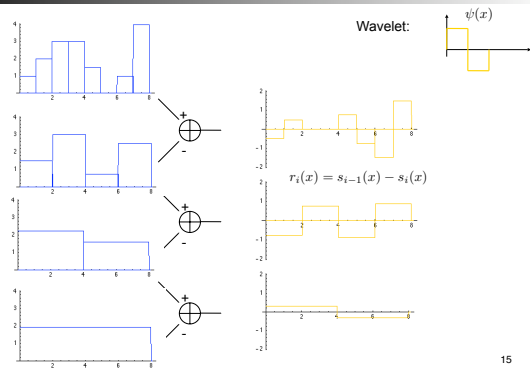
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Wavelets: Haar transform revisited



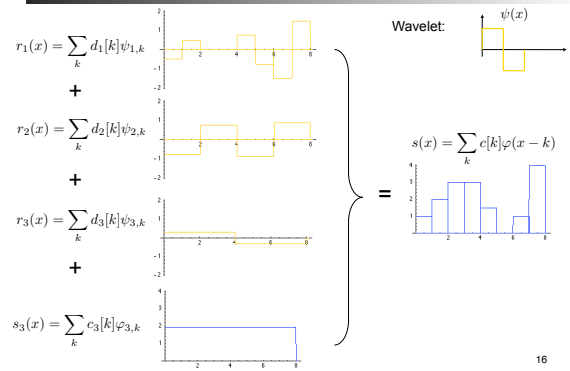
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Wavelets: Haar transform revisited



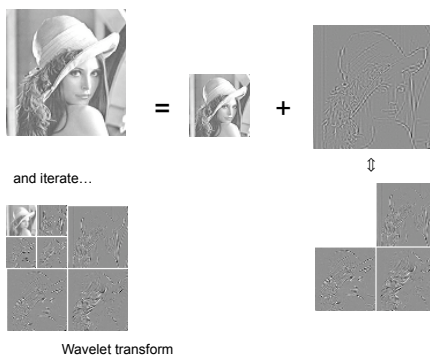
15

Wavelets: Haar transform revisited



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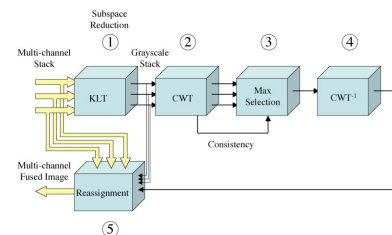
Wavelet transform for images



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Wavelet-based extended depth-of-field

- Simple, wavelet-domain EDF algorithm



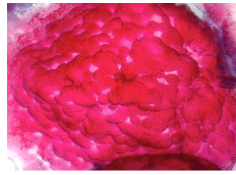
Forster et al., *Microscopy Research and Technique*, 2004

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Extended depth-of-field: results



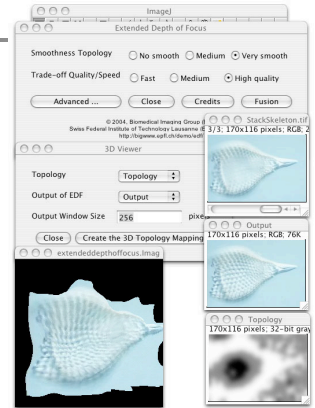
Focal series (z-stack)



In-focus image composite

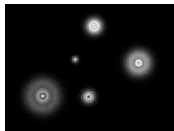
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ImageJ plugin



<http://bigwww.epfl.ch/>

Super-resolution particle localization



Objective:
An efficient approach for locating particles in 3D space

Main challenge:
Axial localization

Characteristics of sub-resolution fluorescent particles

- Diffraction patterns appear in acquired images as particles move out of focus
- Image of a particle: point spread function (PSF) at the corresponding defocus distance

Can the axial position be recovered from out-of-focus acquisitions ?

Solution

Exploit diffraction patterns by fitting acquisitions to a theoretical model

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Defining an image formation model

Principal source of noise:

- Statistical variation in photon arrival rate on CCD
- Follows a Poisson distribution

Acquisition model:

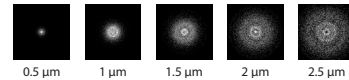
Theoretical PSF with Poisson statistics

Probability of measuring q photons

$$P(q(x, y, z_n | z_p)) = \frac{e^{-\bar{q}(x, y, z_n | z_p)} \bar{q}(x, y, z_n | z_p)^q}{q!(x, y, z_n | z_p)!}$$

\bar{q} : expected photon count, proportional to theoretical PSF intensity:

$$\bar{q}(x, y, z_n | z_p) = c \text{PSF}(x, y, z_n | z_p)$$



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Position estimation

Fitting the experimental data to a theoretical model

Possible criteria:

- Least squares
- Maximum likelihood

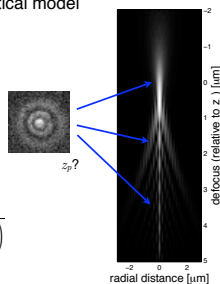
Optimal solution:

- Iterative, based on maximum likelihood

$$z_p^{(k+1)} = z_p^{(k)} - \frac{\sum_{n=1}^N \sum_{(x,y) \in S} \left(\frac{\partial \bar{q}}{\partial z_p} \left(\frac{q}{\bar{q}} - 1 \right) \right)}{\sum_{n=1}^N \sum_{(x,y) \in S} \left(\frac{\partial^2 \bar{q}}{\partial z_p^2} \left(\frac{q}{\bar{q}} - 1 \right) - \left(\frac{\partial \bar{q}}{\partial z_p} \right)^2 \frac{q}{\bar{q}^2} \right)}$$

\bar{q} : expected photon count (theoretical)

q : observed photon count (experimental)



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'Resolution' limits

How can the maximal precision of the estimation be determined ?

Statistical tool: Cramér-Rao bound

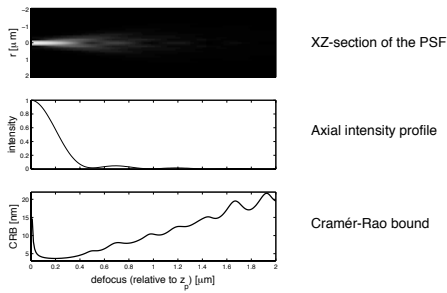
- Theoretical lower bound on the variance of any unbiased estimator
- In short: the performance of the best estimator

$$\text{Var}(\hat{z}_p) \geq 1 / \sum_{n=1}^N \sum_{(x,y) \in S} \bar{q}(x, y, z_n | z_p)^{-1} \left(\frac{\partial}{\partial z_p} \bar{q}(x, y, z_n | z_p) \right)^2$$

- Depends on the theoretical PSF model, thus on acquisition parameters
- Key factor: presence of noise (high amount implies lower precision)

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CRB properties



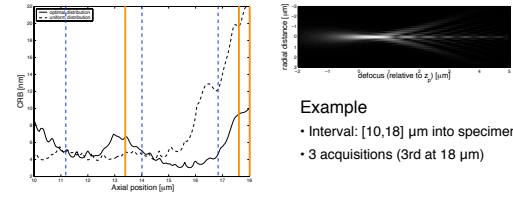
➔ Out-of-focus acquisitions yield better results !!

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CRB: Beyond the theoretical aspects

Optimal experimental acquisition settings can be deduced

- Hypothesis: uniform distribution of particles within a specific section of specimen
- What distribution of focal positions (acquisitions) will yield the lowest CRB ?



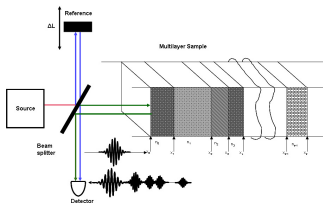
- Example**
- Interval: [10,18] μm into specimen
 - 3 acquisitions (3rd at 18 μm)

Conclusions

- Higher precision can be reached from out-of-focus acquisitions
- Optimal acquisition positions are non-trivial

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Optical coherence tomography (OCT)



- Model of OCT signal

$$i(t) = I_0 + 2\text{Re}\{(h * g)(t)\}$$

I_0 : constant offset

$h(t)$: impulse response of object

$g(t)$: coherence function of light source

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Super-resolution OCT

- Multi-layered model (K interfaces)

$$H(\omega) = \sum_{k=1}^K a_k e^{j b_k \omega}$$

Parameter vector: $\mathbf{p} = (a_1, \dots, a_K, b_1, \dots, b_K)$

(Absorption negligible) $\implies i_{\text{model}}(t; \mathbf{p}) = I_0 + 2 \sum_{k=1}^K a_k g(t - b_k)$

- Estimation method

$$\mathbf{p}_{\text{opt}} = \arg \min_{\mathbf{p}} \left\{ \|i(t) - i_{\text{model}}(t; \mathbf{p})\|^2 \right\}$$

- Non-linear Least Squares (Marquardt-Levenberg)
- Subspace method (direct)

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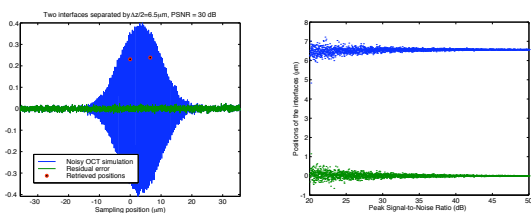
Super-resolution OCT: results

Two layer experiment:

Sub-resolution: $\Delta b = \Delta z / 2$

$$n_{\text{min}} = 1.65$$

$4 \mu\text{m}$



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MULTI-MODALITY IMAGING AND VISUALIZATION

- Image registration (*P. Thévenaz*)
 - Generic problem: multi-modal and time laps sequences
- 3D Rendering (*P. Thévenaz*)
 - High-quality, spline-based isosurfaces

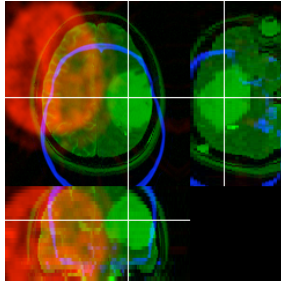


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Multi-modal image registration

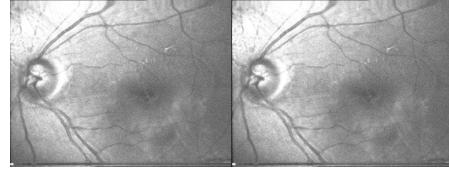
Specificities of the approach

- Criterion: mutual-information
 - Cubic spline model
 - high quality
 - sub-pixel accuracy
- Multiresolution strategy
- Marquardt-Levenberg like optimizer
 - Speed
 - Robustness



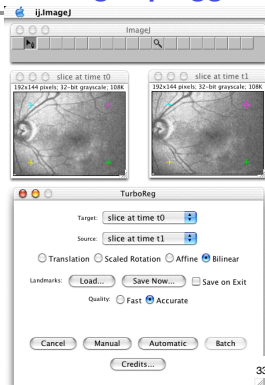
Thévenaz and Unser, *IEEE Trans. Imag Proc.*, 2000

Alignment of image sequences



Software distribution: ImageJ pluggins

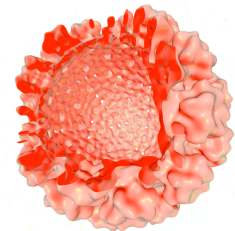
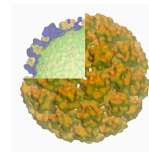
- Software development in JAVA
 - Teaching
 - Student projects
 - Research



<http://bigwww.epfl.ch/>

Visualization

- High-quality methods
 - Splines, ...

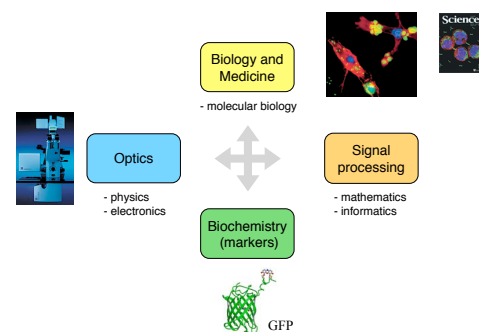


Collaboration with B. Trus, NIH, USA

CONCLUSION

- On-going challenges for bio-imaging
 - Quantitative image analysis
 - Computed imaging: reconstruction, deconvolution, ...
 - 3D + time data: storage, processing and analysis
 - Parametric imaging
- Bio-photonics and signal/image processing
 - Imaging software is becoming part of modern systems
 - Digital optics
- Making algorithms available
 - Platform independence (Java)
 - Web, ImageJ plugins

Global, integrative view of bio-imaging



Acknowledgments

■ Biomedical Imaging Group

Senior scientists:

- Thierry Blu, Ph. D.
- Philippe Thévenaz, Ph.D.
- Daniel Sage, Ph. D.
- Dimitri Van de Ville, Ph.D.
- Brigitte Forster, Ph. D.

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- Rajesh Langoju
- Cedric Vonesch

Former students or collaborators

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- Erik Meijering, Ph.D. (Erasmus Univ.)
- Michael Lieblich (Caltech)

■ Swiss collaborators

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- Harald Hirling, Ph.D.
- Prof. John Maddocks

ISREC

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- Claude Bonnard, Ph.D.

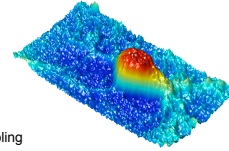
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- Florence Hediger, Ph. D.

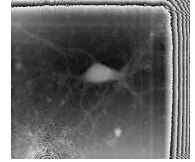
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Image reconstruction and restoration

- 3D reconstruction from projections
- Deblurring, noise reduction
 - *Wavelets, correlation-averaging*
- Digital holography microscopy



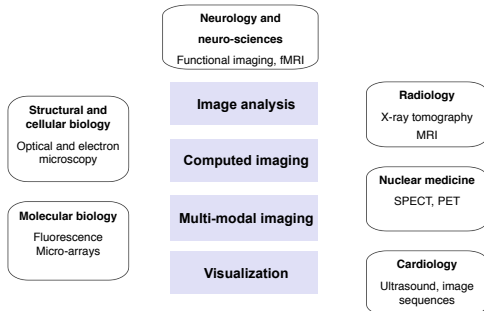
M. Lieblich



Project MICRODIAG, EPFL/UNIL

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Biomedical image processing



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